



COLORADO SCHOOL OF MINES

**ELECTRICAL ENGINEERING DEPARTMENT
EENG 577**

**ADVANCED ELECTRICAL MACHINE DYNAMICS FOR SMART-GRID
SYSTEMS**

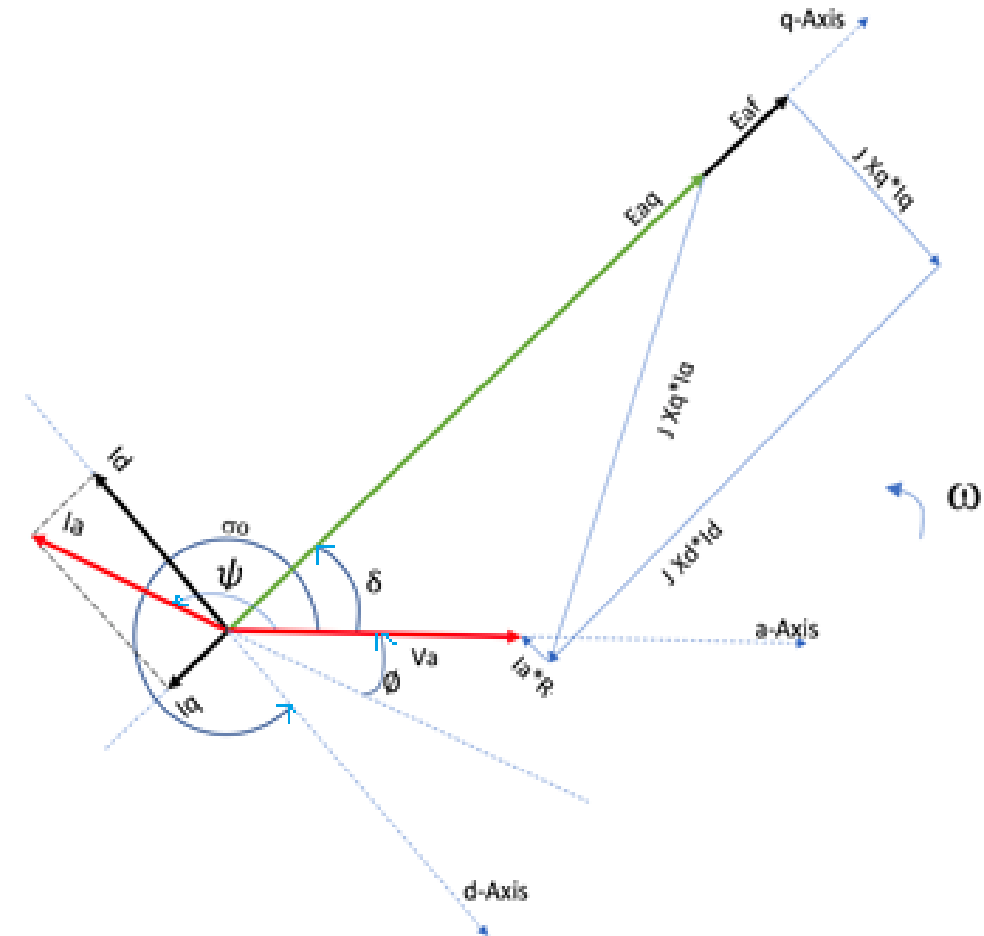
Advanced Topics

Synchronous Machine Initial Conditions

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- **Synchronous Machine Initial Conditions**

- To carry out a State Space (SS) model analysis for a given operating load condition, one needs to compute the suitable excitation currents for all the windings.
- Each operating load condition is represented by an output power, S , a power factor, $\cos(\varphi)$, and an output phase voltage, V_a . These excitation currents are determined from the phasor diagram of the machine.
- A sample phasor diagram representing an overexcited synchronous machine, i.e. the synchronous generator produces both real power, P , and reactive power, Q , is given as shown.



Phasor Diagram of the Synchronous Generator

In a 3-phase balanced system, the voltage expressions are given as:

$$v_{an}(t) = V_m \cos(\omega t)$$

$$v_{bn}(t) = V_m \cos(\omega t - 120^\circ)$$

$$v_{cn}(t) = V_m \cos(\omega t - 240^\circ)$$

Also, the current expressions are given as:

$$i_a(t) = I_m \cos(\omega t - \phi)$$

$$i_b(t) = I_m \cos(\omega t - \phi - 120^\circ)$$

$$i_c(t) = I_m \cos(\omega t - \phi - 240^\circ)$$

In this work, the consumer power notation is being used where generated power is considered negative. Accordingly, if one uses the terminal voltage V_a as a reference, then the current i_a should be in the 3rd quadrant.

The terminal voltage, \overline{V}_a could be expressed as:

$$\overline{V}_a = V_a \angle 0 = V_a + j0$$

The armature phase current, \overline{I}_a , is expressed as:

$$\overline{I}_a = -I_a \cos \phi - jI_a \sin \phi$$

where ϕ is the power factor angle.

The complex power, \overline{S} , is related to the phase voltage and current as follows:

$$\overline{S} = 3\overline{I_a^*} \overline{V_a} = -3I_a V_a \cos \phi - j3I_a V_a \sin \phi$$

The real power is given by:

$$P = -3I_a V_a \cos \phi \quad \text{(Negative, meaning Watts are generated)}$$

and the reactive power is given by:

$$Q = -3I_a V_a \sin \phi \quad \text{(Negative, meaning VARs are generated)}$$

From the above phasor diagram, we can see that the equivalent quadrature axis voltage

\overline{E}_q , is related to the terminal voltage by the following equation:

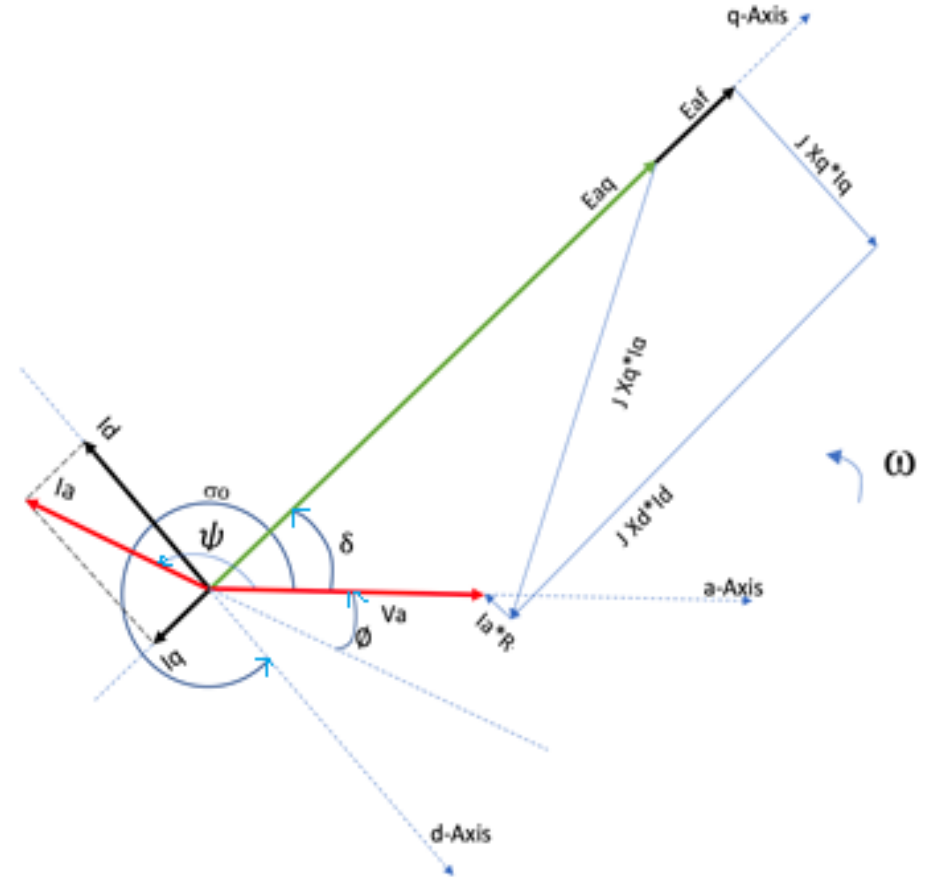
$$\overline{V}_a = \overline{E}_q + jx_q \overline{I}_a + r_a \overline{I}_a$$

We can then write:

$$\overline{E}_q = \overline{V}_a - jx_q \overline{I}_a - r_a \overline{I}_a$$

Neglecting the phase winding resistance r_a , we can write:

$$\begin{aligned} \overline{E}_q &= \overline{V}_a + j0 - jx_q (-\overline{I}_a \cos \phi - j\overline{I}_a \sin \phi) \\ &= (\overline{V}_a - x_q \overline{I}_a \sin \phi) + j(x_q \overline{I}_a \cos \phi) \end{aligned}$$



Accordingly, we can write the following using phasor notation:

$$\overline{E}_q = \sqrt{(V_a + x_q I_a \sin \phi)^2 + j(x_q I_a \cos \phi)^2} \angle \tan^{-1} \left(\frac{x_q I_a \cos \phi}{V_a - x_q I_a \sin \phi} \right)$$

where the angle δ is the torque angle and is given by:

$$\delta = \angle \tan^{-1} \left(\frac{x_q I_a \cos \phi}{V_a - x_q I_a \sin \phi} \right)$$

we also get:

$$\overline{I}_d = \overline{I}_a \sin(\delta + \phi)$$

$$\overline{I}_q = \overline{I}_a \cos(\delta + \phi)$$

$$\overline{E}_{af} = \overline{E}_q + (x_d - x_q) \overline{I}_d$$

The field voltage \overline{E}_{af} is related to the field winding current and mutual inductance between the field and armature windings as follows:

$$E_{af} = \frac{\omega L_{afm} i_f}{\sqrt{2}}$$

The field winding current, i_f , and voltage, V_f , initial conditions can be determined by:

$$i_f = \frac{\sqrt{2} E_{af}}{(\omega L_{afm})} \quad \text{and} \quad V_f = r_f i_f$$

Note also the following from the phasor diagram:

$$\sigma^\circ = \delta + 3\pi/2$$

$$\psi = \pi - \phi$$

$$\overline{E}_{af} = E_{af} \angle \delta$$

REFERENCES

[1] Electric Machinery, by Fitzgerald, Kinsley, and Umans, Recent Edition, McGraw-Hill Publishing Company, Inc., New York, NY.

[2] Arkadan, A.A., VanderHeiden, R.H. and Defenbaugh, J.F., “Effects of Forced Power Transfer on High Speed Generator-Load Systems,” *IEEE Transactions on Energy Conversion*, Vol. 11, No. 2, pp. 344-352, June 1996.